

Heterogeneity and Varying Effect in Hazards Regression: Revisiting the Stanford Heart Transplant Data

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Summary

In the analysis of survival data, when nonproportional hazards are encountered, the popularly used Cox's model (Cox, 1972, JRSS-B **34**, 187-200) is often extended to allow for time-dependent effect by accommodating a varying coefficient. This extension, however, cannot take care of the nonproportionality which is a result of heterogeneity. In contrast, the heteroscedastic hazards regression (HHR) model proposed by Hsieh (2001, JRSS-B **63**, 735-748) is capable of modeling the heterogeneity and thus can be applied when dealing with nonproportional hazards. In this paper, we study the application of the HHR model possibly equipped with varying coefficients. For investigations of the need to impose varying coefficients, an LRR (logarithm of relative risk) plot is suggested. Constancy and degeneration in the plot are used as diagnostic criteria. Two variants of the HHR model, a 'piecewise effect' (PE) analysis and an 'average effect' (AE) analysis, are introduced and implemented using the Stanford Heart Transplant data. Under the framework of the varying-coefficient HHR model, the meanings of the PE and AE analyses, along with their dynamic interpretation, are discussed.

Key words: proportional hazards, varying coefficient, nonproportional hazards, heterogeneity.

1 Introduction

Despite the fact that the proportional hazards (PH) model (Cox, 1972) has been popularly used to analyze survival data, nonproportional hazards among treatments or covariates have also attracted much attention in the past few decades (Stablein and Koutrouvelis, 1985; O'Quigley, 1994). In view of the proportionality, the ratio of hazard rates (or relative risk) associated with different covariate values or their configurations is a time-invariant constant proportional to the difference; additionally the relative risk between groups is homogeneous over strata. Indeed, this is a rather strong assumption. In real applications, however, nonproportionality arises in plots of (cumulative) hazard rates which may indicate that 'time' itself can implicitly be a variable of concern. Statistically, modeling nonproportionality is appealing in that it avoids biased inferences; and a suitable biological model can be essential for the purpose of prediction, in particular on an individual prognosis. A model commonly used is the proportional hazards model equipped with varying coefficients (Murphy and Sen, 1991; Marzec and Marzec, 1997; Martinussen, Scheike, and Skovgaard, 2001):

$$\lambda(t; Z; X) = f_{\lambda_0}(t)g \exp^{-\theta(t)Z(t)}g; \quad (1)$$

where $\theta(t)$ denotes the varying effect of Z . Although the varying-coefficient model (1) has the flexibility of modeling 'nonproportionality' with regards to progressing time, it still is a homogeneous model. Basically, Cox's PH model and the associated partial likelihood inference estimates a mean (or an average) effect at the end of an observational period. When its varying-coefficient setting (1) is used, the covariate effect can theoretically be evaluated at any fixed time, but the effect has the homogeneity property, i.e., some kind of 'average' with regards to the space spanned by the covariate. In other words, the 'homogeneity property' can be viewed as an 'average' taken over different subpopulations represented by different covariate values. When time changes, the average is permitted to differ. Hereafter, this property of variation in time is termed **nonconstancy**. The feature of model (1) brings two aspects of limitations: First, the smoothness of $\theta(t)$ can be very important but hard to ascertain. Second and more importantly, it can be very difficult to interpret $\theta(t)$ biologically.

When 'nonproportionality' is the result of heterogeneity, the heteroscedastic hazards regression (HHR) model proposed by Hsieh (2001) successfully accommodates the nonproportionality from the perspective of variation over different subjects (hereafter termed **heteroscedasticity**):

$$\lambda(t; Z; X) = f_{\lambda_0}(t)g^{\exp(\theta X)} \exp(-\theta Z); \quad (2)$$

where X and Z may be two sets of predictable, time-dependent covariates. In terms of the hazard function, model (2) is written as:

$$\lambda(t; Z; X) = \lambda_0(t) \exp(\theta X) f_{\lambda_0}(t) g^{\exp(\theta X)} \exp(-\theta Z); \quad (3)$$

When $X = Z$, it is the same model studied by Quantin et al. (1996) to test for the proportional hazards assumption. Note that model (2) (or (3)) involves no varying coefficient, but a 'monotone' time-varying effect can still be calculated (see a later context) since there is a

power factor, $\exp(\alpha X)$, of the baseline cumulative hazard. The power factor is a device used to explicitly model the heterogeneity.

According to the previous statement, the heterogeneous effect or nonproportionality can be due to two sources: nonconstancy (variation in time) and heteroscedasticity (variation across subjects). We can thus ask the question: Is there any other source of nonproportionality? In this regard, a straight inclusion of an interaction between 'time' and 'heteroscedasticity' leads to the consideration of time-dependent heteroscedasticity, represented by $\alpha(t)$. So, model (3) can be extended to allow for varying coefficients:

$$\lambda(t; Z; X) = \lambda_0(t) \exp^{\alpha(t)X} g f_{\alpha_0}(t) g^{\exp^{\alpha(t)X} g} \exp^{-\alpha(t)Z} g; \quad (4)$$

where $\exp^{-\alpha(t)Z} g$ is referred to as the λ -component and $\exp^{\alpha(t)X} g$ as the μ -component. Equation (4) is a little sophisticated in its expression. It is not directly integrated to give an more elegant expression in terms of $\alpha(\Phi)$:

$$\alpha(t; Z; X) = f_{\alpha_0}(t) g^{\exp^{\alpha(t)X} g} \exp^{-\alpha(t)Z} g;$$

unless suitable parameterizations of $\lambda(t)$ and $\alpha(t)$ are used. (See the piecewise effect analysis in Section 3.) Moreover, it is also not adequate to directly extend model (2) to the above expression due to a usual requirement that the cumulative hazard increases in time, for fixed X and Z .

Note that when a regressive hazard model is adopted and equipped with varying coefficient(s), it is possibly made more flexible or even more accurate from the viewpoint of statistical modeling. On the other hand, however, conclusions about the implemented varying-coefficient model can only be applied to a more-restricted subpopulation compared to those obtained from using the model without a varying coefficient. By reanalyzing the famous Stanford Heart Transplant (SHT) data (Miller and Halpern, 1982) with consideration of the covariate 'age', in this paper, we study the varying-coefficient HHR model under two of its variants, a piecewise analysis and a 'thus-far-average' analysis, without going into smoothing techniques. We also demonstrate the strategy of diagnosing the nonconstancy and time-dependent heteroscedasticity.

The 'varying effect' property, which entitles this article, of the HHR model ((2) or (4)) needs more explanation. With respect to model (4), first, the varying effect comes from the time-varying coefficients. Second, from model (2), the varying effect is intrinsic in model formulation (Wu, Hsieh, and Chen, 2002). Specifically, let $X = Z$. If the 'effect-measure' is the relative risk (RR), the corresponding hazard function is $\lambda(t; Z) = \mu(Z) f_{\alpha_0}(t) g^{\mu(Z)} \lambda_0(t) \lambda(Z)$, where $\mu(Z) = \exp(\alpha Z)$ and $\lambda(Z) = \exp(-\alpha Z)$; then the logarithm of the relative risk between strata $Z = z_1$ and $Z = z_0$ is

$$\log fRR(t) g = f_{\mu}(z_1) \mu(z_0) g \log f_{\alpha_0}(t) + (\alpha + \lambda)(z_1 \mu z_0); \quad (5)$$

which is obviously a function of time and increases or decreases according to whether $\mu(z_1) > \mu(z_0)$ or $\mu(z_1) < \mu(z_0)$, respectively. The heteroscedasticity of RR is explained by the fact that

it not only depends on the relative difference between z_1 and z_0 , but also on the difference between functions $\lambda(z_1)$ and $\lambda(z_0)$. Here we emphasize that when a varying-coefficient model is used, one has to pay much attention to the interpretation and reasoning behind it, in particular to the dynamics or causal mechanism of what makes the coefficients time dependent.

In the next section, distinction between the PH model and the HHR model is illustrated through several artificial examples by plotting the logarithm of the relative risk (LRR plot). With model (4), since there are three parameters which are dependent on t , estimating equations along with the sieve method, similar to the over-identified estimating equation (OEE) approach (Hsieh, 2001), is introduced in Section 3. When the sieve approximation is used in the analysis of a varying-coefficient model, it involves a suitable partitioning of the time interval. Basically, a reasonable partition cannot be too fine to make each time segment contain enough information (observations), or else the associated estimates of the piecewise coefficients will all be nonsignificant. An alternative consideration is to accumulate the piecewise information and to give a 'thus-far-average' estimate. In Section 4, a 'piecewise effect' (PE) analysis and an 'average effect' (AE) analysis of the SHT data are reported through the implementation of the OEE approach. Hazards-crossing between different age groups is explored and interpreted through the Kaplan-Meier estimates. With the PE analysis, LRR plots among different age groups are displayed to address the existence of nonconstancy and heteroscedasticity. Finally, we give brief discussions on the procedure of modeling heterogeneity, the applicability of the HHR model, and the implication of its varying-coefficient setting.

2 Numerical Examples

Survival data collected from organ transplant or clinical trials often appear to be heterogeneous over one or several variables. If the heterogeneity stems from a dichotomous variable, it can be diagnosed simply by plotting the Kaplan-Meier estimates of the survivor functions for the two groups or their associated cumulative hazard estimates, to see if the proportional hazards rule is sustained (Wu et al., 2002). Note that a possible result of heterogeneity is nonproportionality between different groups. In some cases, nonproportionality can be modeled by (1), in the setting of a varying-coefficient proportional hazards model. When the covariate of concern (say, Z) is itself the source of heterogeneity and it is a continuous variable, however, the application of (1) is limited, and nonproportionality must be carefully diagnosed. With the HHR model and valid estimates, in this paper, we suggest plotting the logarithm of the (estimated) relative risk ($\log \hat{f}_j^\wedge(t; z_j) = \hat{f}_i^\wedge(t; z_i)g$), abbreviated as the LRR plot, where z_j and z_i represent two possible strata of Z . Here we give some artificial examples, in which the LRR plot of the PH model retains the pattern of $\bar{\lambda}(t)$, while the plot under the HHR model is diverse.

Consider a univariate case for the PH model (1), where the expression for the relative risk is $\exp\{\bar{\lambda}(t)(z_j - z_i)g\}$. The LRR plot, $\bar{\lambda}(t)(z_j - z_i)$, has the pattern of $\bar{\lambda}(t)$ except for a scale multiplication which depends only on the difference between covariates for the different strata z_i and z_j . Further consider the HHR model (4) or (2), with or without varying coefficients, where X and Z are taken to be one-dimensional, continuous, and fully identical (i.e., $X = Z$).

In this situation, the heterogeneity is a result of covariate Z (or X) itself. The corresponding relative risk between strata z_i and z_j will be

$$f^{\varpi_0}(t)g^{\beta(z_j) - \beta(z_i)} \exp(f^-(t) + \alpha(t)g(z_j - z_i)); \quad (6)$$

and the LRR plot consists of two components:

$$f^{\beta(z_j) - \beta(z_i)} g \log f^{\varpi_0}(t) + f^-(t) + \alpha(t)g(z_j - z_i); \quad (7)$$

where the pattern of $f^-(t)(z_j - z_i)$ is complicated by the relative difference of the β -component, $\beta(z_j) - \beta(z_i)$, multiplied by $\log f^{\varpi_0}(t)$, as well as by $\alpha(t)(z_j - z_i)$. The following numerical examples illustrate cases in which the nonproportional hazards cannot be fully accounted for by the varying-coefficient PH model.

The rationale of using model (4) rather than (1) is twofold: (i) you add the heteroscedasticity $\exp(\alpha X)$; and (ii) the heteroscedasticity parameter α may also be time varying: $\alpha = \alpha(t)$. Table 1 summarizes several characteristics of the specified model.

[Table 1 about here.]

Throughout these examples, $X = Z$, and Z only takes three values: $z_0 = 0$; $z_1 = 1$; and $z_2 = 2$; the baseline $\varpi_0(t) = \text{texp}(t)$ is used, and $\varpi_0(t) = \int_0^t \varpi_0(u) du$. To illustrate the possibility of a varying-coefficient PH model being capable of treating the crossing hazards phenomenon, i.e., a special case of 'nonproportionality', we choose $f^-(t) = \sin(t/4)$. Case A assumes the varying-coefficient PH model since $\alpha = 0$; Case B and Case C assume the HHR model with fixed and time-varying heteroscedasticities, respectively, when $\alpha = \log 2$ and $\alpha = \sin(t/4)$. The time interval is selected to be $(0; 2)$ for all cases.

[Figures 1(a)»1(d) about here.]

In Figures 1(a) to 1(c), three curves of $\log f_{\beta}(t; z_j) - \log f_{\beta}(t; z_i)g$ are plotted, with the $(j; i)$ pairs equal $(1,0)$, $(2,1)$, or $(2,0)$. In Fig. 1(a), however, only two curves are identified due to the fact that $z_2 - z_1 = z_1 - z_0 = 1$. This can be called a case of degeneration, which results from the model formulation of the 'proportional hazards'. That means, if the covariate values z_i , z_j , and z_k are representatives of some strata with $z_j - z_i = z_k - z_j$, the homogeneity property of the PH model makes two of the curves $\log f_{\beta}(t; z_j) - \log f_{\beta}(t; z_i)g$ and $\log f_{\beta}(t; z_k) - \log f_{\beta}(t; z_j)g$ coincide or become very close in the LRR plot. Moreover, the observed curves retain the same 'shape' as $f^-(t)$ except for being multiplied by the difference of $z_j - z_i$. The situation differs in the HHR model. In Figures 1(b) and 1(c), degeneration is not present, and the relative magnitudes among curves both change in time and are diverse between different $(j; i)$ pairs. In both figures, if the two curves are close at some time, they may be separated some other 'place' (or 'time'). We can say that the existent heterogeneity assures a situation of no degeneration. But it is worth mentioning that if the heteroscedasticity parameter, α , is small or not very significant, degeneration may also take place in the LRR plot. In contrast to Case B, consider an example of time-dependent degeneration such as Case D: $\alpha = \log 2 \mathbb{1}(t > 1)$, where $\mathbb{1}(\cdot)$ is the

indicator function; the other conditions are the same as those of Case B. Case D is designed to illustrate a special case of time-varying heteroscedasticity. The corresponding LRR plot is shown in Fig. 1(d), in which a dramatic change occurs at $t = 1$. When $t \leq 1$, $\alpha = 0$, the phenomena of degeneration and homogeneity observed in Figure 1(a) remain. When $t > 1$, $\alpha = \log 2$, the curves are the same in Fig. 1(b). As a summary, nonproportionality accompanied by 'degeneration' implies that the nonproportionality can be modeled by the conventional PH model with a varying coefficient, $\beta = \beta(t)$; otherwise the nonproportionality should be thought of as a phenomenon of heteroscedasticity which results from the variable 'age' and involves the parameter α in model (4). Furthermore, if degeneration exists at several places but not everywhere, a time-varying coefficient $\beta(t)$ is possible. This means that at the place where there is degeneration, β does not significantly differ from 0; elsewhere, however, β is significant and the heteroscedasticity parameter causes the interrelation among the curves to differ.

3 Estimating Equations and the Sieve Method

Suppose there are n ordered, randomly right-censored observations (survival times or censored times) T_1, T_2, \dots, T_n . Let $h_i(t; Z; X)$ and $N_i(t)$ be the intensity process and counting process for the i th individual and $Y_i(t)$ be the associated at-risk indicator at time t . Further denote

$$\begin{aligned} S_1(t) &= (1-n) \prod_{i=1}^n Y_i(t) \exp(-\int_0^t Z_i(u) f_{\alpha_0}(u) g^{\alpha_i} du); \\ S_Z(t) &= (1-n) \prod_{i=1}^n Y_i(t) Z_i(t) \exp(-\int_0^t Z_i(u) f_{\alpha_0}(u) g^{\alpha_i} du); \text{ and} \\ S_V(t) &= (1-n) \prod_{i=1}^n Y_i(t) V_i(t) \exp(-\int_0^t Z_i(u) f_{\alpha_0}(u) g^{\alpha_i} du); \end{aligned} \quad (8)$$

with predictable time-dependent covariates $Z_i(t)$ and $X_i(t)$. In (8), $f_{\alpha_0} = \exp(\alpha X_i)$, and $V_i(t) = X_i(t)[1 + \exp(\alpha X_i) \log f_{\alpha_0}(t)g]$. By Johansen's decomposition (Johansen, 1983), the full likelihood process has the following form:

$$\tilde{A}(t; \beta; \alpha; \alpha_0) = \int_0^t \frac{h_i(u) dN_i(u)}{S_1(u)} - \int_0^t \frac{Z_i(u) S_Z(u)}{S_1(u)} dN_i(u) - \int_0^t \frac{Z_i(u) S_V(u)}{S_1(u)} dN_i(u) \quad (9)$$

The first factor of (9) is the partial likelihood process. The logarithm of the partial likelihood is

$$l_p(t; \beta; \alpha; \alpha_0) = \sum_{i=1}^n \log \int_0^t \frac{h_i(u) dN_i(u)}{S_1(u)} \quad (10)$$

When time-varying coefficients are not considered, that is when $\beta(t) = \beta$ and $\alpha(t) = \alpha$ in (4), taking partial derivatives of l_p with respect to β and α leads to the following estimating equation processes:

$$\begin{aligned} \sum_{i=1}^n \int_0^t \frac{f_{Z_i} Z_i}{S_1} g dN_i(u) &= 0; \\ \sum_{i=1}^n \int_0^t \frac{f_{V_i} V_i}{S_1} g dN_i(u) &= 0; \end{aligned} \quad (11)$$

Moreover, a Breslow-type estimating equation for the baseline cumulative hazard can be constructed as:

$$\varpi_0(t) = \frac{\sum_{i=1}^n \mathbf{Z}_i^T \mathbf{1}_{\{t \leq Z_i\}} dN_i(u)}{\sum_{i=1}^n Y_i(u) \exp(-\int_0^u \mathbf{Z}_i^T \boldsymbol{\beta} + \int_0^u \mathbf{X}_i^T \boldsymbol{\gamma}) \exp(\int_0^u \mathbf{X}_i^T \boldsymbol{\delta}) du} \quad (12)$$

With model (2), statistical inferences based on a modified partial likelihood, other than the previous estimating equations, are also studied in Bagdonavicius, Hafdi, and Nikulin (2002). Since the baseline $\varpi_0(t)$ is not eliminated in (10), a sieve method (Geman and Hwang, 1982) is used to approximate it. By dividing entire observation period $[0; \tau]$ into m segments by $0 = \tau_0; \tau_1; \tau_2; \dots; \tau_m = \tau$, we have the following approximation of $\varpi_0(t)$:

$$\varpi_0^{(m)}(t) = \sum_{j=1}^m \int_{\tau_{j-1}}^{\tau_j} \mathbf{1}_{\{\tau_{j-1} < u \leq \tau_j\}} du \quad (13)$$

Under the varying-coefficient model (4), a similar approximation can be imposed on $\bar{\cdot}(t)$ and $\circ(t)$, along with a little amendment of the estimating equations.

3.1 Piecewise effect and average effect analyses

Instead of using smoothing techniques, when the sieve approximations are taken for $\bar{\cdot}(t)$ and $\circ(t)$, $\bar{\cdot}(t) \approx \sum_{j=1}^m \bar{\cdot}_j \mathbf{1}_{\{\tau_{j-1} < t \leq \tau_j\}}$ and $\circ(t) \approx \sum_{j=1}^m \circ_j \mathbf{1}_{\{\tau_{j-1} < t \leq \tau_j\}}$, it is termed a 'piecewise effect' analysis of model (4):

$$\varpi_j^{(m)}(t; \mathbf{Z}; \mathbf{X}) = \int_{\tau_{j-1}}^{\tau_j} f \varpi_0^{(m)}(t) g_j^{\beta_j} \mathbf{1}_{\{\tau_{j-1} < t \leq \tau_j\}} \quad (14)$$

where $\varpi_j^{(m)}$ (φ denotes the approximation of ϖ , $g_j^{\beta_j} = \exp(\int_{\tau_{j-1}}^{\tau_j} \mathbf{X}^T \boldsymbol{\beta}$), and $\mathbf{1}_j = \exp(-\int_{\tau_{j-1}}^{\tau_j} \mathbf{Z}^T \boldsymbol{\beta})$. In terms of the cumulative hazard, $\varpi(\varphi)$, model (14) has the following expression:

$$\varpi^{(m)}(t; \mathbf{Z}; \mathbf{X}) = \varpi^{(m)}(\tau_{j-1}; \mathbf{Z}; \mathbf{X}) + [f \varpi_0^{(m)}(t) g_j^{\beta_j} - f \varpi_0^{(m)}(\tau_{j-1}) g_j^{\beta_j}] \mathbf{1}_j; \tau_{j-1} < t \leq \tau_j; \quad (15)$$

with $\varpi^{(m)}(\tau_0; \mathbf{Z}; \mathbf{X}) = \varpi_0^{(m)}(\tau_0) = 0$. The estimating equation for ϖ_0 remains the same, but those for $\bar{\cdot}_j$ and \circ_j become:

$$\begin{aligned} \sum_{i=1}^n \mathbf{Z}_i^T \int_{\tau_{j-1}}^{\tau_j} f \mathbf{Z}_i^T \frac{S_{\mathbf{Z}}^{(m)}}{S_1^{(m)}} g dN_i(u) &= 0; j = 1; 2; \dots; m; \text{ and} \\ \sum_{i=1}^n \mathbf{X}_i^T \int_{\tau_{j-1}}^{\tau_j} f \mathbf{V}_i^T \frac{S_{\mathbf{V}}^{(m)}}{S_1^{(m)}} g dN_i(u) &= 0; j = 1; 2; \dots; m; \end{aligned} \quad (16)$$

where $V^{(m)}$ and $S_K^{(m)}$ are the corresponding V and S_K (for any K) with $\varpi_0^{(m)}(t)$ in place of $\varpi_0(t)$. The parameters $f \int_{\tau_{j-1}}^{\tau_j} g^m$; $f^{\Delta} \int_{\tau_{j-1}}^{\tau_j} g^m$; and $f^{\beta_j} \int_{\tau_{j-1}}^{\tau_j} g^m$ are simultaneously solved from the corresponding estimating equations.

As stated in Sec. 1, when the partition $f \int_{\tau_{j-1}}^{\tau_j} g^m$ gets finer, each segment $(\tau_{j-1}; \tau_j]$ contains smaller number of observations, and the final estimates of $\bar{\cdot}_j$ and \circ_j often will be nonsignificant, a redundant situation when partitioning and modeling of the time-varying coefficient are used.

There is, however, a compromise which lies between the analysis using model (4) without a varying coefficient and the PE analysis. That is, a 'thus-far-average' analysis (hereafter referred to as an 'average-effect' (AE) analysis) can be considered when an average coefficient, $\bar{\beta}_j$ and $\bar{\alpha}_j$, is calculated at each t_j s. In this case, $\beta(t)$ and $\alpha(t)$ are replaced by $\bar{\beta}_j$ and $\bar{\alpha}_j$, for $t \in [t_{j-1}, t_j)$. With the same sieve approximation, the hazard function of the k -th segment (i.e., $t_{k-1} < t \leq t_k$, $k = j$) is

$$h^{(m)}(t; Z; X) = \prod_{k=1}^j f_{\alpha_0}^{(m)}(t) g^{\beta_j i^{1/3} j^{-1}}; t_{k-1} < t \leq t_k; \quad (17)$$

In terms of the cumulative hazard, the AE model is expressed as:

$$H^{(m)}(t; Z; X) = \int_0^t \prod_{k=1}^j \mathbb{1}(t_{k-1} < u \leq t_k) g f_{\alpha_0}^{(m)}(u) g^{\beta_j i^{1/3} j^{-1}} du; \quad (18)$$

Estimation under model (17) can be accomplished by simply replacing the integration interval \int_0^t in (11) and (12) (and thus (13)) by $\int_0^{t_j}$. In this paper, we claim that the AE analysis (17) is simply the HHR model implemented at each time point t_j , $2 \leq j \leq m$. When $j = m$, it is reduced to the ordinary HHR model without varying coefficients. In the following section, the SHT data are analyzed by the PE and AE methods and compared to the result of using the conventional PH model with a varying coefficient.

4 Data Analysis

4.1 Nonproportionality of the Stanford heart transplant data

Analyses of the SHT data (Miller and Halpern, 1982; Lin, Wei, and Ying, 1993) suggested that 'age' and its square (age^2) are important explanatory variables. Since there is nonproportionality among different age groups (see Fig. 2 below), inclusion of the covariate age^2 is to explain the crossing-effect. See also Aitkin, Laird, and Francis (1983) and Arjas (1986, 1988) for more discussion. To deal with the nonproportionality, Marzec and Marzec (1997) fitted the PH model with a varying coefficient on the parsimony of only one covariate, age, and proposed goodness-of-fit tests to demonstrate the validity of their sieve-approximated varying-coefficient setting. The SHT data analyzed in Marzec and Marzec (1997) contain 154 observations (denoted by $T_1 \cdot T_2 \cdot \dots \cdot T_{154}$), of which 102 are noncensored failures. To motivate the accommodation of a heteroscedasticity component by using the HHR model, on the other hand, survivor functions according to different age groups can be displayed. First, the 154 patients are divided into four groups according to the three quartiles of age: 35.25, 44.5, and 49.0. Each group contains 38 or 39 patients. Since there is no significant difference between the younger two groups (logrank statistic=0.0050, p-value=0.9436), we combine them into a single group and denote the patients with $\text{age} < 45$, $45 \leq \text{age} < 49$, and $\text{age} \geq 50$ as groups 1, 2, and 3, respectively. Instead of showing the Kaplan-Meier (K-M) estimates directly, however, we mimic the idea behind the LRR plot in Sec. 2 and display the pairwise log-ratios $\log f_{\hat{\alpha}_2}(t) = \hat{\alpha}_1(t)g$, $\log f_{\hat{\alpha}_3}(t) = \hat{\alpha}_2(t)g$, and $\log f_{\hat{\alpha}_3}(t) = \hat{\alpha}_1(t)g$, where $\hat{\alpha}_j(t) = \int \log f_{\hat{S}_j}(t)g; j = 1; 2; 3$; and $\hat{S}_j(t)$ is the K-M estimate of group j . Since the plot of $\log f_{\hat{\alpha}_j}(t) = \hat{\alpha}_i(t)g$ involves the K-M estimates of groups j and i , the

log-ratio is plotted at the union of the two sets of time points where K-M estimates have been calculated. Plotting the log-ratios, $\log f^{\hat{\alpha}_j}(t) = \hat{\alpha}_i(t)g$, of all possible $(j; i)$ pairs has the merit of exploring pairwise relations among groups. Moreover, proportionality, hazards crossing, and time-varying effect may also be explored. If the proportional hazards rule holds, the ratios must be some constants, although small fluctuations are possible. Otherwise, nonconstancy may exist (which implies $\lambda = \lambda(t)$). Moreover, if a curve crosses the horizon 'log-ratio=0' (the dotted line) at some $t = t_0$, it means that there is a hazards crossing near t_0 between the two associated age groups.

[Figure 2 about here.]

In Fig. 2, the curves show nonproportionality among groups. Moreover, since the interrelations of the three curves change in time, heteroscedasticity may also exist. The existence of time-varying heteroscedasticity will be shown later by the LRR plot. The estimated cumulative hazards of groups 1 and 2, $\hat{\alpha}_1$ and $\hat{\alpha}_2$, cross each other first at a time of between 130 and 250 days, and second at a time of 2127 days. The curve $\log f^{\hat{\alpha}_2} = \hat{\alpha}_1 g$ is basically concave. Another curve, $\log f^{\hat{\alpha}_3} = \hat{\alpha}_1 g$, crosses the horizon 'log-ratio=0' before 25 days and has a similar shape. However, the two curves have different curvature (in terms of t) which results in a third plot, $\log f^{\hat{\alpha}_3} = \hat{\alpha}_2 g$, distinct from the former two. As a whole, the three curves give the impression that the three groups are heteroscedastic, in particular at a time between 200 and 700 days which corresponds to the third segment in the following PE analysis and LRR plot.

4.2 Piecewise effect (PE) analysis and LRR plot

When the HHR model is used, the number of segments, m , for the sieve approximation has to be decided. Since Hsieh (2001) suggested m to be of the order $O(n^{1/3})$ to make the asymptotic results valid, we divide the observation period $[0, 2984]$ into $m = 5$ segments, each containing 30 or 31 observations, failed or censored. In the setting of PE analysis, the parameters are allowed to differ between segments. For the SHT data, the 1- and 3/4 components of the PE model are:

$$\begin{aligned} \lambda_j &= \exp(-\beta_{1j} \text{age} + \beta_{2j} \text{age}^2); \text{ and} \\ \lambda_j &= \exp(\gamma_j \text{age}); \quad \beta_{j-1} < t < \beta_j; j = 1; 2; \dots; 5: \end{aligned} \quad (19)$$

In contrast, Marzec and Marzec's (1997) analysis is basically the varying-coefficient PH model without the covariate age^2 . Thus, their model can be treated as being nested in the current PE model, via which the needs to add age^2 and impose the 3/4-component can be tested by the significance of β_{2j} and β_j . In particular, bias of the effect estimate of age can be avoided because in model (19), heterogeneity has been accounted for by the 3/4-component. Table 2 shows the estimated values of all parameters β_{1j} , β_{2j} , and γ_j which vary from segment to segment, showing the time-dependent 'effect' from the model considered. Among those estimated values of γ_j , in particular, $\gamma_3 (=0.0354)$ significantly differs from zero ($p\text{-value}=0.015$); the estimate β_1 has a $p\text{-value}$ of 0.115, a mild significance of heteroscedasticity for the first segment. This significance

can increase when additional sample is accumulated; that is, when the analysis is extended to the next segment using the following AE method.

When an HHR model has been estimated through the PE analysis, logarithm of the estimated relative risk (LRR) can only be plotted according to several predisposed covariate values. In Fig. 3, LRR plot of three combinations, $\log f_{\cdot}^{\wedge}(t; z_1) = \hat{\cdot}(t; z_0)g$, $\log f_{\cdot}^{\wedge}(t; z_2) = \hat{\cdot}(t; z_1)g$, and $\log f_{\cdot}^{\wedge}(t; z_2) = \hat{\cdot}(t; z_0)g$ are presented for age = 35 (z_0), 45 (z_1), and 55 (z_2), respectively. These values are representative of the three age groups discussed previously and retains the property, $z_1 \leq z_0 = z_2 \leq z_1$, to make a degeneration possible if the underlying model is an homogeneous one (i.e., the PH model with or without a varying coefficient). The curves in Fig. 3 look like (but are not) step functions due to the sieve approximation. In the third segment (i.e., the time interval of [227; 631] days), the three curves are very distinct. In the first segment (i.e., the time interval of (0; 50] days), $\log f_{\cdot}^{\wedge}(t; z_1) = \hat{\cdot}(t; z_0)g$ and $\log f_{\cdot}^{\wedge}(t; z_2) = \hat{\cdot}(t; z_1)g$ are closer to, but still can be distinguished from each other (this can be observed more clearly when the plot is amplified). As for the remaining segments, degeneration becomes clear and heteroscedasticity may disappear. In conclusion, the SHT data appears to be an example of time-dependent degeneration illustrated by the last example in Sec. 2., implying a varying-coefficient $\cdot(t)$.

In practice, one may ask the question: When the true model is the PH model and the HHR model is adopted, will the LRR plot exhibit non-degeneration? The answer relies on the large sample asymptotics of the parameter estimates. For simplicity, let $X = Z$ and $\dim(Z) = 1$. The statistics $(\hat{\cdot}_i; \hat{\cdot}_i^{\circ})^0$ and $\hat{\cdot}_0(t); \cdot_0(t)$ obtained from the OEE method (Hsieh, 2001; Theorem 1) have the order of $O_p(1/\sqrt{n})$. According to (7), the estimated log-relative risk between strata Z_j and Z_i is

$$\begin{aligned} \log \hat{RR} &= \exp f^{\wedge}(z_j; z_i)g \cdot \log f^{\wedge}(\hat{\cdot}_0(t)g + (\hat{\cdot} + \hat{\cdot}^{\circ})(z_j; z_i) \\ &= O_p(1/\sqrt{n}) + \hat{\cdot}(z_j; z_i); \text{ for } 0 < t < 1; \end{aligned} \quad (20)$$

which retains the shape of \cdot (for a large sample size, if the true model is the PH model ($\cdot = 0$ or $\cdot(t) = 0$) and $0 < \cdot_0(t) < 1$ for $0 < t < 1$). When sample size is small, the LRR plot specific to the HHR model may not be 'stable', in particular at the early stage of time.

[Table 2 and Figure 3 about here.]

4.3 Average effect (AE) analysis

A different perspective results in model (17) or (18) when an average effect is of interest even if the effect is time-varying, whereas investigations are made along the time axis so that the information about the model and parameters are collected as a **process**. Specifically, let the estimation be executed at the time points $t_1; t_2; \dots; t_5$. In this case, a thus-far-average estimate is calculated at each t_j , and this estimate has a dynamic meaning with regards to progressing time. It has the interpretation of an ageing effect at the population level. The results of the AE analysis are displayed in Table 3. (The analysis at t_1 is exactly the result of the first segment in the PE analysis and is omitted.)

[Table 3 about here.]

In summary, the difference between the PE and AE analyses is that the PE model is actually an approximation of the varying-coefficient model (4), and it assumes that for each time segment, the coefficients may differ. On the other hand, the AE model is not an approximation of (4). It is simply a practice of the HHR model at the selected times t_1 to t_m . For the goodness-of-fit test for model validity in Table 3, see Hsieh (2001) and Wu, Hsieh, and Chen (2002) for further details. In brief, it is an omnibus test for global adequacy of fitting the HHR model at $t = t_j; j = 2; 3; \dots; 5$, and the constructed testing statistic follows, asymptotically, a chi-square distribution with $3(j - 1)$ degrees of freedom for $2 \cdot j \cdot 5$. From the last panel of Table 3, the results of the goodness-of-fit test show that the HHR model with AE analysis is adequate for $t = t_j; j = 2; 3; \dots; 5$.

4.4 Implication of the results

In terms of the partitions taken for the sieve approximation, there is no segment-to-segment correspondence between the previous analyses and those of Marzec and Marzec (1997). Nevertheless, comparisons can be made by carefully connecting the results of the LRR plot in Fig. 3 and Tables 2 and 3. In our PE analysis, although most of the estimates ($\hat{\alpha}_{1j}; \hat{\alpha}_{2j}; \hat{\alpha}_j; j = 1; \dots; 5$) are not significant, PE analysis is still necessary as the first step to investigate the existence of the varying coefficients. From Table 2, the significance levels of $\hat{\alpha}_1$ (p-value of 0.115) and $\hat{\alpha}_3$ (p-value of 0.015) imply that heteroscedasticity exists in the corresponding periods. The LRR plot displayed in Fig. 3 gives a similar explanation. Since the information used in the PE analysis is accumulated, nonsignificant results appearing in the PE analysis may become significant in the AE analysis. The goodness-of-fit tests for model adequacy in Table 3 reveal that the HHR model is adequate.

As compared with the first analysis (a partition with equal time intervals) of Marzec and Marzec (1997), their first segment, [0,746] days, contains 98 observations, nearly corresponding to the $[T_1; T_{92}]$ interval of our AE analysis in Table 3. However, it should be noted that if a varying-coefficient PH model without heteroscedasticity and which omits the covariate, age^2 , can take care of the nonproportionality, the LRR plots in Fig. 3 should not have this pattern. Degeneration may exist everywhere. In addition, $\hat{\alpha}_{23}$ and $\hat{\alpha}_3$ in the AE analysis should be both nonsignificant since the varying-coefficient PH model can be viewed as a submodel nested in the more-extended varying-coefficient HHR model. From Table 3, since both $\hat{\alpha}_{23}$ and $\hat{\alpha}_3$ are significant (p-values of 0.017 and 0.026) at the level of 0.05, Marzec and Marzec's estimate in this period is a biased one. Under model (4) and its variants (14) and (17), the result of Marzec and Marzec can be reasonably explained by that the influences of omitting the heteroscedasticity and the covariate age^2 cancelling each other. Similarly, in our AE analysis (Table 3), $\hat{\alpha}_5$ is nonsignificant in $[T_1; T_{154}]$, which corresponds to the result of a conventional PH analysis with the covariates of age and age^2 . Finally, although the estimated heteroscedasticity parameter may not be significant in the AE analysis, the heteroscedasticity component $\frac{3}{4} = \exp(\circ \text{age})$ should not be dropped from the analysis due to the fact that, from Fig. 2 and Fig. 3, the

heterogeneity is from the covariate 'age'. This is similar to the concern of 'variable selection' procedures in an ordinary linear regression where variables of interest should always be included. Importantly, with a nonsignificant β_4 component, tests can be improved over those without it.

5 Discussion

To deal with nonproportional hazards, heterogeneity due to variation over subjects is the main focus of the current study. To diagnose heterogeneity, survival data can be grouped according to some important variable (for example, 'age' as in the SHT data). By plotting log-ratio of estimated cumulative hazards of all pairs based on the K-M survivor estimates, firstly, interrelation among age groups can be explored (Fig. 2). If the K-M estimates cross one another at an early stage and the interrelation changes in time, heterogeneity may exist, and incorporation of heteroscedasticity in a Cox-type regression can be taken into consideration. The method of fitting the varying-coefficient PH model to tackle nonproportional hazards phenomena is only feasible when there is no heteroscedasticity. In this paper, we demonstrate that when the nonproportionality is a result of heterogeneity, the varying-coefficient HHR model (4) is applicable. After applying model (4), an LRR plot (Fig. 3) is suggested to diagnose the need of imposing $\beta(t)$ and $\gamma(t)$. Constancy of log-ratios of relative risk and degeneration of some curve(s) are used as criteria. In our analyses of the SHT data, the estimated piecewise parameters differ at various time intervals (the PE model). As well, the average estimates of the three parameters change in a pointwise manner at τ_j (the AE model). From Table 3, β_j s decrease in τ_j . This also implies that there is time-dependent heteroscedasticity when age is the only covariate of concern.

The existent heteroscedasticity may be easily neglected if the varying-coefficient PH model (1) is used. In Table 3, the AE analysis made at τ_5 (that is, the column $[T_1; T_{154}]$) has a nonsignificant estimate of β : $\hat{\beta} = 0.0064$ with a p-value of 0.39. This corresponds to the conventional analysis using the PH model in which age and age² are considered explanatory variables. The inclusion of age² reveals that there is nonproportionality. In the analysis of Marzec and Marzec, the nonproportionality is accounted for by $\beta(t)$ in model (1) where 'age' is the unique explanatory variable. In this paper, however, we demonstrate by the LRR plot of Fig. 3 that there is heterogeneity which can be adequately modeled by a time-dependent heteroscedasticity parameter: $\gamma(t)$. For diagnosing $\gamma(t)$, we suggest using 'degeneration' as a tool for visualization. Moreover, time-dependent degeneration implies time-dependent heteroscedasticity, but not vice versa. In the case when β is not very large, a practitioner need only be concerned with the significance of β and its time-varying properties, while degeneration is a valid criterion of the varying coefficient $\gamma(t)$. As the heteroscedasticity parameter β becomes large, a formal test for its time-varying property along with a companion diagnostic tool still needs to be developed.

In fact, the HHR model is a special case of a transformation model with heteroscedastic error terms (Hsieh, 1995). In this article, we emphasize that adequate modeling of the existent heteroscedasticity can, in some cases, explain the time-varying effect. In addition, coefficients

in the HHR model can also be time dependent. In that case, one has to pay attention to the rationale of using a varying-coefficient setting. If the dynamics of the condition implied by the covariate process or data history can influence the effect and significance of the covariate itself, a varying-coefficient model is reasonable. In an analysis of follow-up experimental data, 'dynamical' meaning can implicitly be designed into the study. For observational data, on the other hand, conclusions about the effects of environmental factors on changes in the health condition or behavior should be drawn carefully.

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Table 1: Specified conditions for the varying-coefficient PH and HHR models. A general formula of the assumed model is: $\lambda_j(t; \mathbf{Z}; \mathbf{X}) = \lambda_{j0}(t) \exp(\alpha_0(t) \mathbf{g}^T \exp(\int_0^t \mathbf{Z} \mathbf{g}_i^T \exp(-\int_0^s \mathbf{g}^T \mathbf{Z} \mathbf{g}_i^T ds) \mathbf{g}^T \mathbf{Z} \mathbf{g}_i^T ds))$, in which we choose \mathbf{X} and \mathbf{Z} to be identical. Case A assumes a varying-coefficient PH model. Cases B and C assume HHR models with fixed and time-varying heteroscedasticities, respectively. Case D specifies an HHR model with time-dependent degeneration, a special case of time-varying heteroscedasticity.

Parameters	$\alpha_0(t) = t \exp(t)$	
	$\sigma^2(t) = \sin(1/4t)$	
Covariate	$z_0 = 0; z_1 = 1; z_2 = 2$	

Case A	$\sigma^2 = 0$	PH model
Case B	$\sigma^2 = \log 2$	HHR model with fixed heteroscedasticity
Case C	$\sigma^2 = \sin(1/4t)$	HHR model with time-varying heteroscedasticity
Case D	$\sigma^2 = \log 2 \mathbb{1}(t > 1)$	HHR model with time-dependent degeneration

Table 2: Analyses of SHT data using the piecewise effect method calculated at $t = \tau_j$ (meaning $\tau_1 = T_{30}; \tau_2 = T_{61}; \dots; \tau_5 = T_{154}$.) Values in parentheses are the p-values of the associated Wald tests for significance.

	$[T_1; T_{30}]$	$(T_{30}; T_{61}]$	$(T_{61}; T_{92}]$	$(T_{92}; T_{123}]$	$(T_{123}; T_{154}]$
$j =$	1	2	3	4	5
β_{1j}	-0.0959 (0.2650)	-0.1580 (0.8357)	0.0116 (0.9476)	-0.1128 (0.8950)	-0.2380 (0.8660)
β_{2j}	0.0016 (0.1444)	0.0032 (0.0255)	-0.0014 (0.6749)	0.0022 (0.5064)	0.0039 (0.4656)
β_j	0.0160 (0.1147)	-0.0086 (0.9903)	0.0354 (0.0150)	-0.0110 (0.9807)	-0.0098 (0.9885)

Table 3: Analyses of SHT data using the average effect method calculated at $t = t_j; j = 2; 3; 4; 5$. Values in parentheses are the p-values of the associated tests for significance of parameters or the model. For $j = 1$, the AE analysis is exactly the PE analysis in Table 2, so it is omitted from this table. The last panel shows the goodness-of-fit test for model validity.

	$[T_1; T_{61}]$	$[T_1; T_{92}]$	$[T_1; T_{123}]$	$[T_1; T_{154}]$
$j =$	2	3	4	5
$\hat{\beta}_{1j}$	-0.1424 (0.0372)	-0.1217 (0.0593)	-0.1207 (0.0442)	-0.1300 (0.0237)
$\hat{\beta}_{2j}$	0.0023 (0.0076)	0.0020 (0.0165)	0.0019 (0.0111)	0.0021 (0.0047)
$\hat{\beta}_j$	0.0174 (0.0037)	0.0137 (0.0257)	0.0079 (0.3014)	0.0064 (0.3927)
Goodness-of-fit test	6.12 $[\hat{A}_3^2]$ (0.1059)	8.82 $[\hat{A}_6^2]$ (0.1834)	10.18 $[\hat{A}_9^2]$ (0.3356)	18.03 $[\hat{A}_{12}^2]$ (0.1149)